Chapter 23: Linear, second-order differential equations

A linear, second-order differential equation has the form:

$$\ddot{y}(t) + \alpha_1 \dot{y}(t) + \alpha_2 y(t) = \beta$$

Solving linear, autonomous, second-order differential equations

- 1. Write in general form: $\ddot{y}(t) + \alpha_1 \dot{y}(t) + \alpha_2 y(t) = \beta$
- 2. Use the **characteristic equation** $r^2 + \alpha_1 r + \alpha_2 = 0$ to find the roots (r). The lowest root is always the first root(r_1) you use in the homogeneous solution.
- 3. Compute the homogeneous solution:

$$y_h(t) = C_1 e^{r1t} + C_2 e^{r2t}$$
 if r_1 is not equal to r_2

$$C_1 e^{rt} + C_2 t e^{rt}$$
 if $r_1 = r_2 = r$

4. Compute particular solution:

$$y_p(t) = \beta / \alpha_2$$
 if α_2 is not 0

5. Report general solution

$$y(t) = y_h(t) + y_p(t)$$

- 6. Compute constants C_1 and C_2 such that the initial conditions are satisfied
- 7. Report solution. Substitute the answers of step 6 into the general solution to find the end solution.

The solution of a linear, second-order differential equation only **converges** toward to steady-state equilibrium if the roots of the characteristic equation are negative.

Solving linear, non-autonomous, second-order differential equations

- 1. Write in general form: $\ddot{y}(t) + \alpha_1 \dot{y}(t) + \alpha_2 y(t) = \beta(t)$
- 2. Use the **characteristic equation** $r^2 + \alpha_1 r + \alpha_2 = 0$ to find the roots (r). The lowest root is always the first root(r₁) you use in the homogeneous solution.
- 3. Compute the homogeneous solution:

$$y_{L}(t) =$$

$$C_1e^{r1t} + C_2e^{r2}$$

 $y_h(t) = C_1 e^{r1t} + C_2 e^{r2t}$ if r_1 is not equal to r_2

$$C_1 e^{rt} + C_2 t e^{rt}$$
 if $r_1 = r_2 = r$

if
$$r_1 = r_2 = r$$

4. Compute the particular solution with the **method of undetermined coefficients:**

$$y_n(t) = A_n t^n + A_{n-1} t^{n-1} + ... + A_1 t + A_0$$

Differentiate this formula to $\dot{y}(t)$ and $\ddot{y}(t)$. Plug these two formulas into the general form en than solve for all A's

5. Report general solution

$$y(t) = y_{h}(t) + y_{p}(t)$$

- 6. Compute $\mathrm{C_1}$ and $\mathrm{C_2}$ such that the initial conditions are satisfied
- 7. Report solution. Substitute the answers of step 6 into the general solution to find the end solution.